



A Survey of Frequent Subgraphs and Subtree Mining Methods

Hamed Dinari and Hassan Naderi

Department of Computer Engineering
Iran University of Science and Technology
Tehran, Iran

ABSTRACT

A graph is a basic data structure which, can be used to model complex structures and the relationships between them, such as XML documents, social networks, communication networks, chemical informatics, biology networks, and structure of web pages. Frequent subgraph pattern mining is one of the most important fields in graph mining. In light of many applications for it, there are extensive researches in this area, such as analysis and processing of XML documents, documents clustering and classification, images and video indexing, graph indexing for graph querying, routing in computer networks, web links analysis, drugs design, and carcinogenesis. Several frequent pattern mining algorithms have been proposed in recent years and every day a new one is introduced. The fact that these algorithms use various methods on different datasets, patterns mining types, graph and tree representations, it is not easy to study them in terms of features and performance. This paper presents a brief report of an intensive investigation of actual frequent subgraphs and subtrees mining algorithms. The algorithms were also categorized based on different features.

Keywords

Graph Mining, Subgraph, Frequent Pattern, Graph indexing.

1. INTRODUCTION

Today we are faced with ever-increasing volumes of data. Most of these data naturally are of graph or tree structure. The process of extracting new and useful knowledge from graph data is known as graph mining [1] [2] Frequent subgraph patterns mining [3] is an important part of graph mining. It is defined as “process of pattern extraction from a database that the number frequency of which is greater than or equal to a threshold defined by the user.” Due to its wide utilization in various fields, including social network analysis [4] [5] [6], XML documents clustering and classification [7] [8], network intrusion [9] [10], VLSI reverse [11], behavioral modeling [12], semantic web [13], graph indexing [14] [15] [16] [17] [18], web logs analysis[19], links analysis[20], drug design [21] [22] [23], and Classification of chemical compounds[24] [25] [26], this field has been subject matter of several works.



The present paper is an attempt to survey subtree and subgraph mining algorithms. A comparison and classification of these algorithms, according to their different features, is also made. The next section discusses the literature review followed by section three that deals with the basic ideas and concepts of graphs and trees. Mining algorithms, frequent subgraphs are discussed in section four from different viewpoint such as criteria of representing graphs (adjacency matrix and adjacency list), generation of subgraphs, number of replications, pattern growth-based and apriori-based classifications, classification based on search method, classification based on transactional and single inputs, classification based on type of output, and also Mining based on the logic. Fifth section focuses on frequent Mining algorithm from different angles such as trees representation method, type of algorithms input, tree-based Mining, and Mining based on Constraints on outputs.

2. RELATED WORKS

H.J.Patel¹, R.Prajapati, et al. [27] Classified graph mining and mentioned two types of the algorithms, apriori-based and pattern growth based. K.Lakshmi¹, T.Meyyappan [28] studied apriori based and pattern growth based, taking into account aspects such as input/output type, how to display a graph, how to generate candidates, and how many times a candidates is repeated in the graph dataset. In [29] D.Kavitha, B.V.Manikyala, et al. suggested the third type of graph mining algorithms named as inductive logic programming. Here a complete survey of graph mining concepts and a very useful set of examples to ease the understanding of the concept come next.

3. BASIC CONCEPTS

3.1 Graph

A graph $G (V, E)$ is composed of a set of vertices (V) connected to each other by and a set of edges (E).

3.2 Tree

A tree T is a connected graph that has no cycle. In other words, there is only and only one path between any two vertices.

3.3 Subgraph

A **subgraph** $G' (V', E')$ is a subgraph of $G (V, E)$, which vertices and edges are subsets of V and E respectively:

- $V' \subseteq V$
- $E' \subseteq E \wedge ((v_1, v_2) \in E' \rightarrow v_1, v_2 \in V')$



One may say that a subgraph of a graph is a pattern of that graph. Concerning trees two types of patterns can be defined:

3.3.1 Induced pattern

The definition is exactly the same as the definition of subtree in a tree (Figure.1.a, Figure.1.c). It means that the vertices and the edges of Figure.1.a. Can be seen in Figure.1.c as well

3.3.2 Embedded pattern:

Almost the same as induced pattern, except that there may be one or more supplementary vertices between the two parents and child nodes of pattern, For example vertex **A** in Figure.1.c is parent of vertex **D**; and in Figure.1.b an embedded pattern of Figure 1.c is seen.

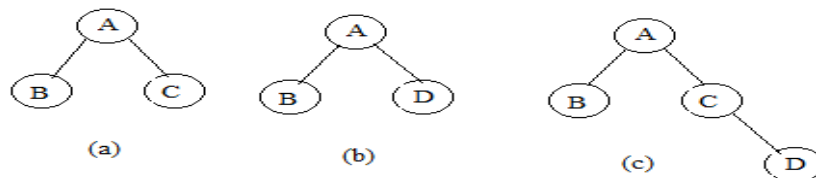


Figure.1. An example of the Induced and embedded subtree pattern

3.3.3 Isomorphism

Two graphs are **isomorph**, if there are one to one relationships among their vertices and edges.

3.3.4 Frequent Subgraph

Suppose a graph G and a set of graphs $D = \{g_1, g_2, g_3, \dots, g_n\}$ are given, $\text{support}(G)$ is:

$$\text{Support}(G) = \frac{\text{number of graphs in } D \text{ that contain } G}{|D|}$$

A graph G in a dataset D is called **Frequent** if its support is not less than of a predefined threshold.

4. AN OVERVIEW OF FREQUENT SUBGRAPH MINING ALGORITHM ACCORDING TO DIFFERENT CRITERIA

This section discusses different criteria for classification of frequent graph mining algorithms, including: graph representation, input type, constraint-based, inductive logic programming, search strategy, and completeness/-incompleteness of outputs.

4.1 Graph Representation

4.1.1 Adjacency Matrix

A graph can be demonstrated as an adjacency matrix, in this case the row and the column represent vertex of graph and the entries represents edges of graph (i.e. when there is an edge between two vertices, entries constituted by the junction of the row and the column is filled by “1” and otherwise by



”0”). Furthermore, the nodes are represented on the main diameter of the matrix (Figure.2). To Show the graph as a string a combination of nodes and edges as a sequence in particular order can be used, and since every permutation of the nodes may generate a specific string, a series of maximum or minimum canonical adjacency matrix (CAM) must be taken into account. An advantage of this is that two isomorphism graphs will have the same maximum/minimum CAM.

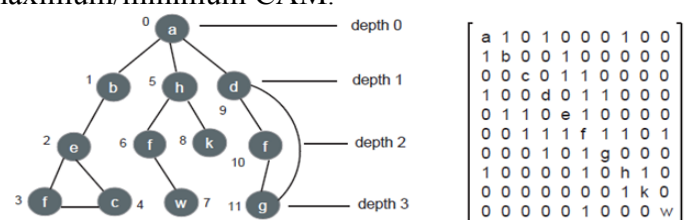


Figure.2. Left side a graph and right side corresponding adjacency matrix

4.1.2 Adjacency List

Another way to represent a graph is adjacency list. When the graph is sparse, several “zeros” are generated in the adjacency matrix, which is a great waste of memory and to avoid this, adjacency list is an answer as it assigns memory dynamically

4.2 Subgraph Generation

Two subgraphs can be mixed to generate candidate subgraph and the result will be a new subgraph. However, given that many copied subgraphs might be generated in the mixing process, the way of generating candid subgraphs is critical. Among the available methods are extension and right most expansion. In the latter case, the subgraphs are expanded in one direction and no duplicate candidate is generated.

4.3 Frequency Counting

To check if the generated candidates is a duplicate or not, the frequency of each must be determined and compared with the support value. Of the data structures, which are used to count the frequency of each candidate are embedding list and TSP tree.

5. A SURVEY OF FREQUENT SUBGRAPH MINING ALGORITHMS

5.1 Classification Based on Algorithmic Approach

5.1.1 Apriori-Based (Breadth First Search)

This category of algorithms uses generates and test method and surface search to find a subgraph from the network that consist the database. Therefore, before the subgraph with length of $k + 1$ ($(k+1)$ -candidate), all frequent subgraphs with length of k must be found. Thus, each candidate with length of $k + 1$ is obtained by connecting two frequent subgraphs with



length of k . However, in this method, all state of candidate subgraph generated is considered. Maintenance and processing need plenty of time and memory, which tackles the performance [30] [2].

5.1.2 Pattern Growth-Based

In FP-growth-based methods a candidate subgraph with length of $k+1$ is obtained by extending a frequent pattern with length of k . Since extending a frequent subgraph with length of k may generate several candidate of length $k+1$, thus the way a frequent subgraph is expanded is critical in reducing generation of copied subgraphs. Table 1 lists apriori and pattern growth algorithms [2].

Table 1. Frequent Subgraph Mining Algorithms

Pattern Growth	Apriori
GSPan [41]	FARMER [31]
CloseGraph [42]	FSG [3]
Gaston [43]	HSIGRAM
TSP [44]	GREW [32]
MOFa [45]	FFSM [4]
RP-FP [46]	ISG
RP-GD [46]	SPIN [33]
JPMiner [47]	Dynamic GREW [34]
MSPAN	AGM [35]
VSIGRAM [48]	MUSE [36]
FPF [49]	SUBDUE [37]
Gapprox [50]	AcGM [38]
HybridGMiner	DPMine
FCPMiner [51]	gFSG [39]
RING [52]	MARGIN [40]
SCMiner [53]	
GraphSig [54]	
FP-GraphMiner [55]	
gPrune [56]	
CLOSECUT [57]	
FSMA [58]	

5.2 Classification Based on Search Strategy

There are two search strategies to find frequent subgraphs. These two methods include breadth first search (BFS) and depth first search (DFS).

5.3 Classification Based on Nature of the Input

Depending on input type of algorithms, here tried to be divided two categories presented as following:



5.3.1 Single Graph Database

Database consists of a single large graph

5.3.2 Transactional Graph Database

Database consists of a large number of small graphs. Figure.3 shows a database consist of a set of graphs and two subgraphs and their frequency. In Figure.3 (left side, g, g2, and g2) demonstrates a transactional graph database and frequency of two frequent subgraphs (right side).

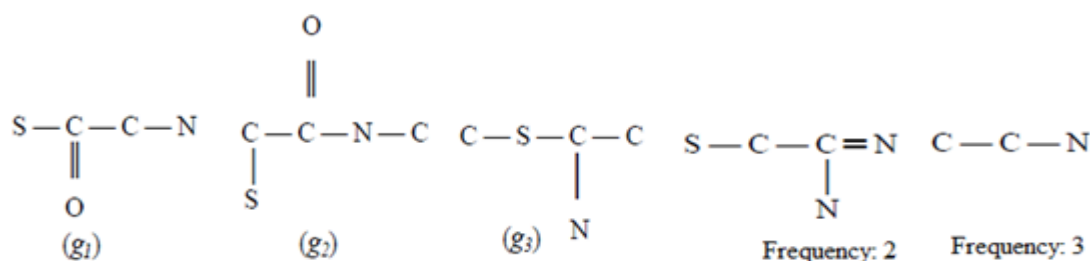


Figure.3. A database consisting of three graph g1, g2, g3 and two subgraph and frequency of each

5.4 Classification Based on Nature of the Output

5.4.1 Completeness of the Output

While, some algorithms find all frequent patterns, some other only mines part of frequent patterns. Frequent patterns mining is closely related to performance. When the total size of dataset is too high, it is better to use algorithms that are faster in execution so that reduction of the performance is avoided, although, not all frequent patterns are minded. Table 2 lists the completeness of output [29].

Table 2. Completeness of Output

Incomplete Output	Complete Output
SUBDUE	FARMER
GREW	gSpan
CloseGraph	FFSM
ISG	Gaston
	FSG
	HSIGRAM

5.4.2 Constraint-Based

With increase of size database, the number of frequent pattern is increased. This makes maintenance and analyzing more difficult as it needs more memory space. Reducing the number of frequent patterns without losing the data is achievable through mining and maintains more comprehensive patterns. Given that each pattern satisfies the condition of being frequent the



whole subset satisfies the condition, to achieve more comprehend patterns we can use the following terms:

5.4.2.1 Maximal Pattern

Subgraph g_1 is maximal pattern if the pattern is frequent and does not consist of any super-pattern, so that $g_2 \not\supset g_1$.

5.4.2.2 Closed Pattern

Subgraph g_1 is closed if it is frequent and does not consist of any frequent super-pattern such as g_2 , $g_2 \supset g_1$ (i.e. support). Table 3 lists maximal and closed subgraph algorithms.

Table 3. Frequent Subgraph Mining (Constraintd)

Closed	Maximal
CloseGraph	SPIN
CLOSECUT	MARGIN
TSP	ISG
RP-FP	GREW
RP-GD	

5.5 Logic-Based Mining

Also known as inductive logic programming, which also an area of machine learning, mainly in biology. This method uses inductive logic to display structured data. ILP core uses the logic to display for search and the basic assumptions of that structured way (e.g. WARMR, FOIL, and C-PROGOL), which is derived from background knowledge [29]. Table 4 lists the Pattern Growth and Table 5 indicates apriori-based algorithms categorized from different aspects [59] [27] [60] [61] [62] [28] [30] [63].

Table 4. Frequent Subgraph Mining Algorithms (Pattern Growth-based)

Algorithms	Input Type	Graph Representation	Subgraph Generation	Frequency Counting
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GSpan	Set of graphs	Adjacency Matrix	Rightmost Extension	DFS
CloseGraph	Set of graphs	Adjacency Matrix	Rightmost Extension	DFS
Gaston	Set of graphs	Hash Table	Extension	DFS
TSP	Set of graphs	Adjacency Matrix	Extension	TSP Tree
MOFA	Set of graphs	Adjacency Matrix	Rightmost Extension	DFS
RP-FP	Set of graphs	Adjacency Matrix	Rightmost Extension	DFS
RP-GD	Set of graphs	Adjacency Matrix	Rightmost Extension	DFS
JPMiner	Set of graphs	Adjacency Matrix	Rightmost Extension	DFS
MSPAN	Set of graphs	Adjacency Matrix	Rightmost Extension	DFS
FP-Graph-Miner	Set of graphs	BitCode	Extension	DFS
gPrune	Set of graphs	Adjacency matrix	Iteration	M-DFSC
FSMA	Set of graphs	incident matrix	Extension	Normalize Matrix
RING	Set of graphs	Invariant vector	Extension	R-tree, DFS
GraphSig	Set of graphs	Feature vector	Merge and Extension	DFS

Table 5. Frequent Subgraph Mining Algorithms (Apriori-based)

Algorithms	Input Type	Graph Representation	Subgraph Generation	Frequency Counting
SUBDUE	Single Large Graph	Adjacency Matrix	Level-wise Search	MDFS
FARMER	Graph	Trie structure	Level-wise Search, ILP	Trie data structure
FSG	Set of graphs	Adjacency List	One Edge Extension	TID list
HSIGRAM	Set of graphs	Adjacency Matrix	Iterative Merging	Maximal independent set
GREW	Single large Graph	Sparse graph	Iterative Merging	Maximal independent set
FFSM	Single large Graph	Adjacency Matrix	Merging and Extension	Suboptimal canonical adjacency matrix tree
ISG	Set of graphs	Edge Triple	Edge Triple Extension	TID List
SPIN	Set of graphs	Adjacency Matrix	Join Operation	Canonical Spanning Tree
Dynamic	Set of graphs	Sparse graph	Iterative Merging	Suffix trees
GREW	Set of graphs	Adjacency Matrix	Vertex Extension	Canonical Labeling
AGM	Set of graphs	Search Tree	Disjunctive Normal Form	DFS coding
MUSE	Set of graphs	Lattice	Join	CAM
MARGIN	Set of graphs	Adjacency Matrix	Join	CAM
AcGM	Set of graphs	Adjacency Matrix	Join	CAM
gFSG	Set of graphs	Adjacency Matrix	Iterative Merging	Hashtree

Here several algorithms related to graph/tree mining are discussed in more details.

• **Gp-Growth Algorithm**

The algorithm consists of three main steps:

1. Candidate generation by join operation.



2. Using a new method for tree representation and look up table that allows quick access to the information nodes in the candidate generation phase without having to read the trees of the database.
3. using right most expansion to candidate generation that guaranteed not generate duplicate candidate.

This algorithm uses lookup table that is implemented as Hash table to store input trees information. It is the key part, represented as the pair of (T,pos), where T is identification of input tree and *pos* is number in preorder traversal, and value part, represented as (l,s), where l is label and s is scope of node. In this algorithm a new candidate is generated using scope of each node That means, first node, which is added to the other node should be added along the right most expansion and that within the scope of the first node to be added continually this process other frequent pattern is found [64].

• *Fp-Graph Miner Algorithm*

This algorithm uses FP-growth method to find frequent subgraphs, Its input is a set of graphs (Transactional database). First a BitCode for each edge is defined, then a set of edge is defined for each edge .When, edge is found in the each of graphs, the BitCode is '1' and otherwise '0'. Then a frequency table is sorted in ascending order based on equivalent BitCode belongs to each edge and afterward, FP tree is constructed and frequent subgraphs are obtained through depth traversal [55].

6. FREQUENT SUBTREES MINING ALGORITHMS CLASSIFICATION

6.1 Trees Representation

A tree can be encoded as a sequence of nodes and edges. Some of most important ways of encoding trees are introduced below:

6.1.1 DLS (Depth Label Sequence)

Let T be a Labeled Ordered Tree and depth-label pairs including labels and depth for each node are belonged to V. For example, (d(vi),l(vi)) are added to string *s* throughout DFS traversal of tree *T*. Depth-label sequence of tree *T* is obtained as { d(v1), l(v1)), ..., (d(vk), l(vk)) }. For instance, DLS for tree in **Figure.4** can be presented as follow:

{(0,a),(1,b),(2,e),(3,a),(1,c),(2,f),(3,b),(3,d),(2,a),(1,d),(2,f)(3,c)}

6.1.2 DFS – LS (Depth First Sequence)-(Label Sequence)

Assumed a labeled ordered tree, Labels $\forall vi \in V$ is added to string of *s* during the DFS traversal of Tree *T*. During backtrack '-1' or '\$' or '/' is added



to the string, DFS-LS code for tree T is illustrated in in Figure.4
 $\{abea\$\$\$cfb\$d\$\$a\$\$dfc\$\$\$ \}$

6.1.3 BFCS (Breadth First Canonical String)

Let T be an unordered tree. Several sequence encoded string can be generated using the BFS method and through changing the order of children of a node. Thus, one may say that BFCS tree T equals to the smallest lexicographic order of this encoded string. BFCS of tree T is showed in Figure.4. $\{a\$bcd\$e\$fa\$f\$a\$bd\$\$c\# \}$

6.1.4 CPS (Consolidate Prufer Sequence)

Let T be a labeled tree T , and CPS encoding method consists of two parts: NPS as extended prufer sequence, which uses vertex numbers traversal as set of unique label is obtained; an d LS (Label Sequence) as a sequence consisting of labels in prefix traversal after the leafs is removed is achieved. Both NPS and LS generate a unique encoding for labeled tree. NPS and LS obtained for the tree presented in Figure.4 is as follow respectively: $\{ebaffccafda-\}$, $\{aebbbdfaccfda\}$. To obtain NPS, a leaf from the tree is removed in each step and the parent of the leaf is taken get as output. This is repeated until only the roots remain and '-' is added to note as the end of the string. Regarding LS (Label Sequence) the same postfix traversal of the tree is taken as LS. Table9 remarks this category of trees [65].

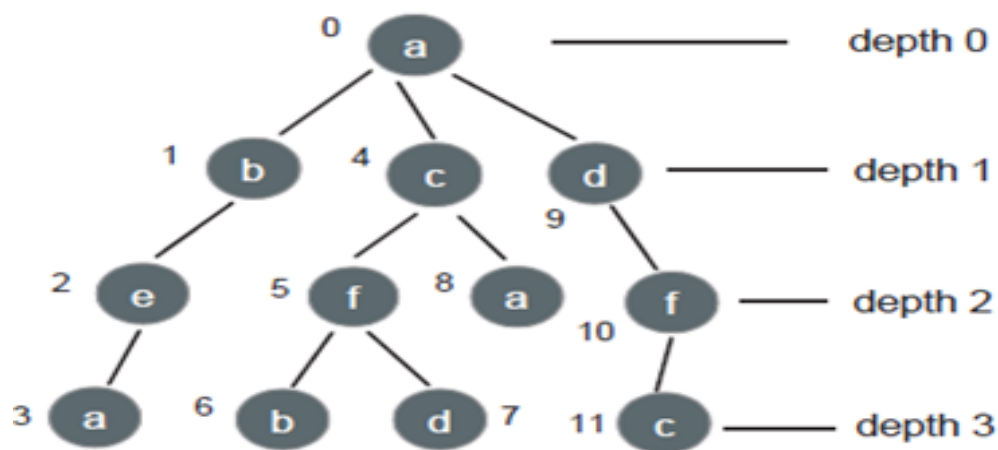


Figure.4. A Tree Example

**Table 6. Frequent subtree Mining Algorithms (Tree Representation)**

Algorithms	Tree Representation
uFreqt	DLS
SLEUTH	DFS-LS
Unot	DLS
Path Join	FST-Forest
RootedTreeMiner [66]	BFCS
FREQT	DLS
TreeMiner	DFS-LS
Chopper	DLS
XSPanner	DLS
AMIOT	DFS string
IMB3Miner	DFS-LS
TRIPS	CPS
FreeTreeMiner	BFCS
CMTreeMiner	DFS-LS
HybridTreeMiner [67]	BFCS
GP-Growth	DFS-LS

6.2 Input Types

6.2.1 Rooted Ordered Trees

Rooted Ordered sub-tree is a kind of tree in which a single node is considered as the “root” of the tree and there is a relationship between children of each node so that each child is greater than or equal to its siblings that are placed at the left hand side of it; moreover it is less than or equal to ones that are placed at its right hand side. If we elate or definition of rooted ordered tree such that there was no need to consider the relationship between siblings we have a rooted unordered sub-tree.in Table7 rooted ordered tree mining algorithms is shown.

Table 7. Rooted Ordered Tree mining Algorithms

Embedded	Induced
TreeMiner [71]	FREQT [68]
Chopper [72]	AMIOT [69]
XSPanner [72]	IMB3Miner [70]
IMB3-Miner	TRIPES [65]
	TIDES [65]

6.2.2 Rooted Unordered Trees

In this type of trees, a node is considered as the root, however, there is no particular order between the descendants of each node,In Table 8 rooted unordered tree mining algorithms is listed.

**Table 8. Rooted unordered Tree mining Algorithms**

Embedded	Induced
TreeFinder	uFreqT [73]
Cousin Pair [77]	Unot [74]
SLEUTH [78]	PathJoin [65]
	Rooted TreeMiner [75]
	TreeFinder [76]

6.3 Tree Base Data Mining

Frequent subtrees mining algorithm can be categorized into two major categories, apriori-based and pattern growth-based. Table 9 lists the apriori and pattern growth algorithms of trees [79] [76] [80].

Table 9. Frequent Subtree Mining Algorithms

Pattern Growth	Apriori
uFreqt	TreeFinder
Unot	AMIOT
FREQT	FreeTreeMiner
TRIPS	TreeMine [81]
TIDES	SLEUTH
Path Join	CMTreeMiner [82]
XSPanner	Pattern Matcher [71]
Chopper	W3Miner [83]
PrefixTreeISpan [86]	FTMiner [84]
PCITMiner [87]	CFFTree [85]
F3TM [88]	IMB3-Miner
GP-Growth [64]	

7. CONCLUSIONS AND FUTURE WORKS

Frequent subgraph Mining algorithms were first examined from different viewpoints such as different ways of representing a graph (e.g. adjacency matrix and adjacency list), generation of subgraphs, frequency counting, pattern growth-based and apriori-based algorithm classification, search based classification, input-based classification (single, transactional), output based classification. Furthermore, Mining based on logic was discussed. Afterward, frequent subtrees traversal algorithms were examined from different viewpoints such as trees representation methods, type of inputs, tree-based traversal, and also Mining based on Constraints of outputs. Given the results, it is concluded that in absence of generating patterns by pattern-



growth, it is featured with less computation work and needs smaller memory size. Moreover, these algorithms are specifically designed for trees and graphs and cannot be used for other purposes. On the other hand, as they work on variety of datasets, it is not easy to find tradeoffs between them. The same frequent patterns can be used for searching similarity, indexing, classifying graphs and documents in future studies. Parallel methods and technologies such as Hadoop can also be needed when working with excessive data volume.

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